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Computer simulation of bottle-brush polymers with flexible backbone: Good solvent versus theta solvent conditions

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By molecular dynamics simulation of a coarse-grained bead-spring-type model for a cylindrical molecular brush with a backbone chain of \(N_b\) effective monomers to which with grafting density \(\sigma\) side chains with \(N\) effective monomers are tethered, several characteristic length scales are studied for variable solvent quality. Side chain lengths are in the range \(5 \leq N \leq 40\), backbone chain lengths are in the range \(50 \leq N_b \leq 200\), and we perform a comparison to results for the bond fluctuation model on the simple cubic lattice (for which much longer chains are accessible, \(N_b \leq 1027\), and which corresponds to an athermal, very good, solvent). We obtain linear dimensions of the side chains and the backbone chain and discuss their \(N\)-dependence in terms of power laws and the associated effective exponents. We show that even at the theta point the side chains are considerably stretched, their linear dimension depending on the solvent quality only weakly. Effective persistence lengths are extracted both from the orientational correlations and from the backbone end-to-end distance; it is shown that different measures of the persistence length (which would all agree for Gaussian chains) are not mutually consistent with each other and depend distinctly both on \(N_b\) and the solvent quality. A brief discussion of pertinent experiments is given. © 2011 American Institute of Physics. [doi:10.1063/1.3656072]

I. INTRODUCTION

Macromolecules which consist of a “backbone” polymer, to which flexible or stiff side chains are grafted, the so-called “bottle-brush polymers,” find very great interest recently (see Refs. 1–6 for reviews). Varying the chemical nature of both the backbone chain and the side chains, their chain lengths \((N_b, N)\) and the grafting density \(\sigma\), the structure of these cylindrical molecular brushes can be widely varied. That is, their local “thickness” as measured by the cross-sectional radius \(R_c\) or linear dimensions of individual side chains can be varied as well as their local “stiffness,” traditionally measured by “the” persistence length \(l_p\) and their effective contour length \(L_c\). Here, we use quotation marks with respect to “the” persistence length, because there is evidence, at least for the case of very good solvent conditions, that a unique persistence length measuring the “intrinsic” stiffness of a polymer cannot be defined in the standard fashion.10, 11 Now an intriguing observation12 is the sensitivity of the large-scale structure of these bottle-brush polymers to solvent quality: one finds a thermally induced collapse of single macromolecules from cylindrical brushes to spheres, in a very small temperature range, and it is speculated that these bottle-brushes could be useful as building blocks of “soft nanomachines.”12 We also note that biopolymers with comblike architecture are ubiquitous in nature (such as proteoglycans13 or the aggregate molecules that play a role in the soft lubricating layers in human joints.14), and probably in this context temperature and/or solvent quality (or \(pH\) value) are relevant parameters as well.

In view of these facts, a comprehensive clarification of how the properties of bottle-brush polymers depend on solvent quality clearly would be interesting. Although there are occasional experimental reports, how particular linear dimensions of these polymers scale in various solvents (e.g., Refs. 15–18), we are not aware of a systematic study of this problem. While work based on self-consistent field theory (SCFT) predicted already very early in Ref. 19 that the side chain gyration radius \(R_g\) scales as \(R_g \propto N^{3/4}\) for good solvents and \(R_g \propto N^{2/3}\) for theta solvents, there is now evidence from experiment, simulation, and theory that these power laws apply if at all only for side chain lengths \(N\) of the order of \(10^3\), which are of no practical relevance: Experiments have only studied the range \(N < 10^2\), and the range accessible in simulations3, 6, 10, 20–26 is similarly restricted. Numerical modeling applying the Scheutjens-Fleer version of SCFT has given clear evidence27 that even within this mean-field
approach $N \approx 10^3$ is needed to reach the regime, where the predicted power laws\cite{19, 28} apply. While the investigation of the scaling (self-similar) properties of bottle-brushes with extremely long backbone chains and very long side chains may be a challenging theoretical problem, it is of little relevance for the experimentally accessible systems, and clearly not in the focus of the present paper. Both the SCFT theories\cite{19, 27} and the scaling theories\cite{20} consider ideal chains aiming to describe the behavior at the theta temperature, while previous simulations have almost exclusively considered the good solvent case only. Notable exceptions are studies of globule formation of bottle-brushes with very short side chains ($N = 4-12$) under poor solvent conditions\cite{30} and the study of microphase separation of bottle-brushes with straight backbones in poor solvent.\cite{31, 32}

The present work intends to make a contribution to close this gap, by presenting a simulation study of a coarse-grained bead-spring (BS)-type model of bottle-brush polymers where the solvent quality is varied from very good solvent conditions to the theta point regime. In Sec. II, we shall describe the model and simulation technique, while in Sec. III we present our numerical results. In Sec. IV, a summary is given as well as an outlook on pertinent experiments.

II. MODEL AND SIMULATION METHOD

Extending our previous work on the simulation of bottle-brush polymers with rigid backbones,\cite{31, 32} we describe both the backbone chain and the side chains by a bead-spring model,\cite{33, 36} where all beads interact with a truncated and shifted Lennard-Jones (LJ) potential $U_{LJ}(r)$ and nearest neighbors bonded together along the chain also experience the finitely extensible nonlinear elastic potential $U_{FENE}(r)$, $r$ being the distance between the beads. Thus

\begin{equation}
U_{LJ}(r) = 4\varepsilon_{LJ} \left[ \left( \frac{\sigma_{LJ}}{r} \right)^{12} - \left( \frac{\sigma_{LJ}}{r} \right)^{6} \right] + C, \quad r \leq r_c,
\end{equation}

while $U_{LJ}(r > r_c) = 0$, and where $r_c = 2.5\sigma_{LJ}$. The constant $C$ is defined such that $U_{LJ}(r = r_c)$ is continuous at the cutoff. Henceforth, units are chosen such that $\varepsilon_{LJ} = 1$, $\sigma_{LJ} = 1$, the Boltzmann constant $k_B = 1$, and in addition also the mass $m_{LJ}$ of beads is chosen to be unity. The potential Eq. (1) acts between any pair of beads, irrespective of whether they are bonded or not. For bonded beads additionally the potential $U_{FENE}(r)$ acts,

\begin{equation}
U_{FENE}(r) = -\frac{1}{2}k r_0^2 \ln \left[ 1 - \left( \frac{r}{r_0} \right)^2 \right], \quad 0 < r \leq r_0,
\end{equation}

while $U_{FENE}(r > r_0) = \infty$, and hence $r_0$ is the maximal distance that bonded beads can take. We use the standard choice $r_0 = 1.5$ and $k = 30$. Related models have been used with great success to study the classification of polymer melts formed from short chains\cite{37} and to study the effects of solvent quality of polymer brushes on flat planar substrates.\cite{38} For such models of brushes on a planar substrate, the implicit solvent model (Eq. (1)) has been compared with models using explicit solvent molecules, and it was found that the results are very similar.

Note that in our model there is no difference in interactions, irrespective of whether the considered beads are effective monomers of the backbone or of the side chains, implying that the polymer forming the backbone is either chemically identical to the polymers that are tethered as side chains to the backbone, or at least on coarse-grained length scales as considered here the backbone and side chain polymers are no longer distinct. There is also no difference between the bond linking the first monomer of a side chain to a monomer of the backbone and bonds between any other pairs of bonded monomers. Of course, our study does not address any effects due to a particular chemistry relating to the synthesis of these bottle-brush polymers, but as usually done,\cite{36, 39, 40} we address universal features of the conformational properties of these macromolecules.

There is one important distinction relating to our previous work\cite{31, 32} on bottle-brush polymers with rigid backbones: following Grest and Murat,\cite{41} there the backbone was taken as an infinitely thin straight line in continuous space, thus allowing arbitrary values of the distances between neighboring grafting sites, and hence the grafting density $\sigma$ could be continuously varied. For the present model, where we disregard any possible quenched disorder resulting from the grafting process, of course, the grafting density $\sigma$ is quantized: we denote here by $\sigma = 1$ the case that every backbone monomer carries a side chain, $\sigma = 0.5$ means that every second backbone monomer has a side chain, etc. Chain lengths of side chains were chosen as $N = 5, 10, 20, 40$, while backbone chain lengths were chosen as $N_b = 50, 100, 200$, respectively.

It is obvious, of course, that for such short side chain lengths any interpretation of characteristic lengths in terms of power laws, such as $R_c \propto N^{\nu} a$, is a delicate matter, $\nu$ being an “effective exponent” and characterizes only the specified range of rather small values of $N$ and not the limit $N \rightarrow \infty$ considered by most theories.\cite{2, 19, 27-28} Thus, the actual value of $\nu$ is of limited interest, it only gives an indication to which part of an extended crossover region the data belong. However, we emphasize that (i) our range of $N$ nicely corresponds to the range available in experiments;\cite{1, 14, 15-18, 26, 41-43} (ii) The analysis in terms of power laws with effective exponents is a standard practice of experimentalists in this context (e.g., Refs. 1 and 17).

We recall that for linear chains, the theta temperature for the present (implicit solvent) model has been roughly estimated\cite{44} as $T_\theta \approx 3.0$ (note, however, that there is still some uncertainty about the precise value of $T_\theta$ for a similar model\cite{45} the correct value of $T_\theta$, $T_\theta \approx 3.18$ in this case, could only be established for chain lengths exceeding $N = 200$). Thus, in the present work we have thoroughly studied the temperature range $3.0 \leq T \leq 4.0$. From previous work\cite{46} on rather long chains in polymer brushes on flat surfaces, using the same model (Eqs. (1) and (2)) to describe the interactions, it is known that for $T = 4.0$ one finds a behavior characteristic for (moderately) good solvents. Very good solvent conditions could be obtained from a slightly different model that has extensively been studied for standard polymer brushes,\cite{36, 47} where in Eq. (1) the cutoff is chosen to coincide with the minimum of the potential, $r_c = 2^{1/6}\sigma_{LJ}$ (and then also $T = 1$ can be chosen for this essentially athermal model). Rather
than carrying out simulations for bottle-brushes using this model, we found it more appropriate to compare to the athermal version of the bond fluctuation model on the simple cubic lattice, which describes very good solvent conditions and has been used in our earlier work.

The use of this model has several advantages: (i) due to the fact that excluded volume constraints can be monitored via the occupancy of lattice sites, a very efficient implementation of the pivot algorithm in this Monte Carlo approach has become possible.

Therefore, very large bottle-brush polymers can be equilibrated, up to \( N_b = 1027 \), a task that is very difficult to achieve by molecular dynamics (MD) methods. (ii) The extent to which the bond fluctuation model and MD results agree (for comparable choices of parameters) yields some insight to what extent the pre-asymptotic regime that we study is model dependent. Of course, a truly universal behavior (apart from amplitude prefactors) can only be expected for the asymptotic cases studied, and we have concluded that for our largest systems studied (shown in Fig. 1(c), with a total number of 8000 effective monomers) the statistical effort is not yet sufficient.

However, since the application of the athermal version of the bond fluctuation model (BFM) to the simulation of bottle-brush polymers is well documented (Hsu and Paul have given a careful discussion on the effort needed for the BFM to sample equilibrium properties) in the recent literature, we do not give any details here.

In the MD simulation, the positions \( \mathbf{r}_i(t) \) of the effective monomers with label \( i \) evolve in time \( t \) according to Newton’s equation of motion, amended by the Langevin thermostat:

\[
m_{iJ} \frac{d^2 \mathbf{r}_i(t)}{dt^2} = -\nabla U_i(\{\mathbf{r}_j(t)\}) - \gamma \frac{d\mathbf{r}_i}{dt} + \mathbf{\Gamma}_i(t),
\]

where \( U_i(\{\mathbf{r}_j(t)\}) \) is the total potential acting on the \( i \)th bead due to its interactions with the other beads at sites \( \{r_i(t)\} \), \( \gamma \) is the friction coefficient, and \( \mathbf{\Gamma}_i(t) \) is the associated random force. The latter is related to \( \gamma \) by the fluctuation-dissipation relation

\[
\langle \mathbf{\Gamma}_i(t) \cdot \mathbf{\Gamma}_j(t) \rangle = 6k_BT \frac{\gamma}{m_{iJ}} \delta_{ij} \delta(t - t').
\]

Following previous work we choose \( \gamma = 0.5 \), the MD time unit

\[
\tau_{iJ} = \left( \frac{m_{iJ} \sigma_{iJ}^2}{\epsilon_{iJ}} \right)^{1/2},
\]

being also unity, for our choice of units. Equation (3) was integrated using the leap frog algorithm with a time step \( \delta t = 0.006 \tau_{iJ} \), and utilizing the GROMACS package. For the calculation of properties of the bottle-brushes, typically 500 statistically independent configurations are averaged over.

Of course, for bottle-brushes with large \( N_b \) equilibration of the polymer conformations is a difficult problem. Since we expect that end-to-end distance \( R_e \) and gyration radius \( R_g \) of the whole molecule belong to the slowest relaxing quantities, we studied the autocorrelation function of \( R_g^2 \) to test for equilibration,

\[
\phi(t) = \frac{\langle (R^2_g(t' + t) - R^2_g(t'))(R^2_g(t') - R^2_g) \rangle}{\langle (R^2_g(t') - R^2_g)^2 \rangle}, \quad (6)
\]

Note that \( R^2_g \) means an average of \( R^2_g(t') \) over the time \( t' \) in the MD trajectory (and the average \( \langle \cdots \rangle \) is computed by averaging over 500 statistically independent runs). Despite a substantial investment of computer time, \( \phi(t) \) still exhibits significant fluctuations (remember that quantities such as \( R_e \) and \( R_g \) are known to exhibit a “lack of self-averaging,” respect of how large \( N_b \) is). Figure 1 gives some examples for \( \phi(t) \). If the number of samples would be infinite and \( \delta t \rightarrow 0 \), we should expect a monotonous decay of \( \phi(t) \) towards zero as \( t \) becomes large. Due to the fact that the number of samples is not extremely large, and \( \delta t \) is not extremely small, Fig. 1 gives clear evidence for noise that is still correlated. We see that for small \( N \) the noise amplitude starts out at \( \pm 0.1 \), and the time scale on which the fluctuations of \( \phi(t) \) change sign is at \( t \approx 1500 \tau_{iJ} \) in (a), \( t \approx 1000 \tau_{iJ} \) in (b), and \( t \approx 2000 \tau_{iJ} \) in (c). While in cases (a) and (b), the (statistically meaningful) initial decay of \( \phi(t) \) occurs so fast that it can only be seen on a magnified abscissa scale (inserts), we see that in (c) the initial decay is also much slower, and the associated time scale is of the same order as the time over which fluctuations are correlated. We have carefully considered \( \phi(t) \) for all cases studied, and we have concluded that for our largest system studied (shown in Fig. 1(c), with a total number of 8000 effective monomers) the statistical effort is not yet sufficient to allow meaningful conclusions on the overall linear dimensions of the bottle-brush, while in all other cases the effort was judged to be sufficient. The damped oscillatory character of the relaxation seen particularly in Fig. 1(c) could be a matter of concern; we attribute this relaxation behavior to particular slow collective motions (breathing-type modes) of the chain.

Figure 2 shows a small selection of snapshot pictures of equilibrated bottle-brush polymers. From these snapshot pictures, it is already clear that the side chains cause a significant stiffening of the backbone, at least on a coarse-grained scale, and that bottle-brushes where \( N_b \) is not very much larger than \( N \) look like wormlike chains. This conclusion corroborates pictures generated experimentally (by atomic force microscopy or electron microscopy techniques, e.g., Refs. 1, 4, and 56), but this observation should not mislead one to claim that the Kratky-Porod wormlike chain model often employed to analyze such micrographs provides an accurate description of bottle-brush polymers as we shall see.

Of course, both the bead-spring model and the BFM are idealizations of realistic comb-branched polymers, where also bond-angle potentials and torsional potentials are present and contribute to the local chain stiffness. Thus it is gratifying to note that nevertheless measured structure factors of real

\[
\phi(t) = \frac{\langle (R^2_g(t' + t) - R^2_g(t'))(R^2_g(t') - R^2_g) \rangle}{\langle (R^2_g(t') - R^2_g)^2 \rangle}, \quad (6)
\]
bottle-brush polymers\cite{42} can be mapped almost quantitatively to their simulated BFM counterparts,\cite{36} if the lattice spacing is fixed at a length of a few angstroms, and about three chemical monomers are mapped onto two effective monomers of the BFM. Residual minor discrepancies may, to some extent, be due to solvent quality effects.\cite{36}

III. SIDE-CHAIN AND BACKBONE LINEAR DIMENSIONS AND ATTEMPTS TO EXTRACT “THE” PERSISTENCE LENGTH OF BOTTLE-BRUSH POLYMERS

Figure 3 presents log-log plots of the normalized mean square gyration radius of the side chains $\langle R^2_{gs} \rangle / l^2_b N$ as a function of time $t$ in units of $t_{LJ}$ for several cases: $\sigma = 0.5, N_b = 100, N = 10, T = 3.0$ (a); $\sigma = 1.0, N_b = 100, N = 20, T = 3.0$ (b); and $\sigma = 1.0, N_b = 200, N = 40, T = 3.0$ (c). The fluctuations of $\phi(t)$ change sign initially at $t \approx 1500t_{LJ}$ (a), $t \approx 10000t_{LJ}$, and $t \approx 20000t_{LJ}$ (c) as shown in the inserts.

FIG. 1. Plot of $\phi(t)$ (see Eq. (6)) versus the time $t$ in units of $t_{LJ}$. Several cases are shown: $\sigma = 0.5, N_b = 100, N = 10, T = 3.0$ (a); $\sigma = 1.0, N_b = 100, N = 20, T = 3.0$ (b); and $\sigma = 1.0, N_b = 200, N = 40, T = 3.0$ (c). The fluctuations of $\phi(t)$ change sign initially at $t \approx 1500t_{LJ}$ (a), $t \approx 10000t_{LJ}$, and $t \approx 20000t_{LJ}$ (c) as shown in the inserts.

FIG. 2. Selected snapshot pictures of equilibrated configurations of bottle-brush polymers. Backbone monomers (when visible) are displayed in magenta (darker grey color), side chain monomers in green (lighter grey). Cases shown refer to $\sigma = 0.5, N_b = 100, N = 10, T = 3.0$ (a) and $T = 4.0$ (b), as well as $\sigma = 1.0, N_b = 100, N = 20, T = 3.0$ (c) and $T = 4.0$ (d).

FIG. 3. Log-log plot of mean square radius of gyration of the side chains normalized by their chain length and by the square bond length $l^2_b$ between successive monomers, $\langle R^2_{gs} \rangle / l^2_b N$, versus side chain length $N$, for $\sigma = 0.5$ (a) and $\sigma = 1.0$ (b). Data for the bead-spring model at two temperatures ($T = 3.0$ and $T = 4.0$), as indicated in the figure, are included, as well as three backbone chain lengths ($N_b = 50, 100,$ and $200$, respectively). For comparison, also data for the athermal bond fluctuation model for comparable backbone chain length are included. Straight lines indicate effective exponents $\nu_{\text{eff}} \approx 0.60$ ($T = 3.0$) or $\nu_{\text{eff}} \approx 0.63$ ($T = 4.0$) in case (a), and $\nu_{\text{eff}} \approx 0.60$ ($T = 3.0$) or $\nu_{\text{eff}} \approx 0.64$ ($T = 4.0$) in case (b). For the bond fluctuation model under very good solvent conditions the slightly larger effective exponent $\nu_{\text{eff}} \approx 0.65$ for $\sigma = 0.5$, and $\nu_{\text{eff}} \approx 0.66$ for $\sigma = 1.0$) than for the off-lattice model with $T = 4.0$ results.
function of side chain length $N$ ($l_b$ is the bond length between successive monomers), comparing data for grafting densities $\sigma = 0.5$ and $\sigma = 1.0$, and two temperatures ($T = 3.0$ and $T = 4.0$, respectively). Three different backbone lengths ($N_b = 50, 100,$ and $200$), respectively. All data are for the bead-spring model and $\sigma = 1.0$. Data for bottle-brush polymers with flexible backbone are connected by curves to guide the reader’s eyes. Data are only shown for $T = 3.0$ and $4.0$ for the rigid backbone case.

We have also checked that for the bead-spring model average side chain linear dimensions for bottle-brushes with rigid and flexible backbones are identical for the bond fluctuation model, at least in the accessible parameter regime. For the bond fluctuation model a similar equivalence has been found also for the radial density profile of the monomers. Figure 4 shows then the temperature dependence of $\langle R_{gs}^2 \rangle$ for the different choices of $N_b$, demonstrating that the side chain extension is independent of $N_b$ and agrees well between rigid and flexible backbones. The small deviations observable between the rigid and the flexible backbone cases for large $N$ are due to residual systematic errors of the simulations for the flexible backbone. The present work, therefore, suggests that the equivalence between bottle-brushes with rigid and flexible backbones carries over to chains in variable solvent quality, down to the theta point (but we caution the reader that this equivalence will break down for poor solvents, in the regime of intermediate grafting densities where for rigid backbones bead-necklace structures occur).

The straight lines on the log-log plots in Fig. 3 illustrate the empirical power law

$$\langle R_{gs}^2 \rangle \propto N^{2\nu_{eff}},$$

consistent with corresponding experiments (see Refs. 1 and 4 and references quoted therein) and we find that $\nu_{eff}$ decreases with decreasing solvent quality and with decreasing grafting density. In the good solvent regime, $\nu_{eff} > \nu = 0.588$, the established value of the exponent describing the swelling of linear polymers under good solvent conditions, $R_g(N) \propto N^\nu$ for $N \to \infty$. As expected, $\nu_{eff}$ is still distinctly smaller than the value predicted from scaling, $\nu_{eff} = 2\nu/(1 + \nu) \approx 0.74$ or SCFT, but the slight enhancement of $\nu_{eff}$ with respect to its value for free chains ($\nu = 1/2$) at the theta point, $T = 3.0$; $\nu = 0.588$ for good solvents) is evidence that the side chains interact with each other, which is a prerequisite for the expected induced stiffening of the backbone chain.

We now turn to the backbone linear dimensions. Here, we first caution the reader that in good solvent conditions we clearly also expect that the mean square end-to-end distance of a bottle-brush polymer satisfies the standard scaling relation

$$\langle R_{eb}^2 \rangle \propto N_b^{2\nu}, \quad \nu = 0.588, \quad N_b \to \infty,$$  

but the longer the side chain length the larger $N_b$ must be chosen such that Eq. (8) can be verified. We start the discussion with data from the bond fluctuation model, where (for $N \leq 24$) data up to $N_b = 1027$ are available. Figure 5 hence shows a log-log plot of $\langle R_{eb}^2 \rangle / (2l_b^2 N_b^{2\nu})$ versus $N_b$ of the factor of 2 in the denominator is arbitrarily chosen, since for Gaussian chains ($\nu = 1/2$) the result would simply be the persistence length $\ell_p$ in units of the bond length. Thus, it was suggested that

$$\ell_p \propto N_b^{1/2}.$$
in the excluded volume case one could introduce an effective persistence length \( l_{p,R}(N) \) via the definition

\[
l_{p,R}(N) = \left( \frac{R_{eb}^2}{2N_b^2} \right), \quad N_b \to \infty.
\] (9)

Then Fig. 5 can be interpreted as a plot of \( l_{p,R}(N)/l_b \) versus \( N \) in the region where it is basically independent of \( N_b \). The quantity \( l_{p,R}(N) \) defined in this way is compatible with an effective power law,

\[
l_{p,R}(N) \propto N^\xi,
\] (10)

but the effective exponent \( \xi \) clearly depends on \( N_b \), if \( N_b \) is not chosen large enough (Fig. 6). Thus, Fig. 5 clearly shows that \( l_{p,R}(N) \) is not a quantity characterizing the intrinsic stiffness of a bottle-brush polymer. For large \( N_b \), the exponent \( \xi \) seems to saturate at a value close to 0.65 and 0.74 for \( \sigma = 0.5 \) and \( \sigma = 1.0 \), respectively, but for chain lengths \( N_b \) in the range from \( N_b = 67 \) to \( N_b = 131 \) it is only in the range from \( \xi = 0.41 \) to \( \xi = 0.55 \) and from \( \xi = 0.48 \) to \( \xi = 0.67 \) for \( \sigma = 0.5 \) and \( \sigma = 1.0 \), respectively.

Thus, it is no surprise that for the bead-spring model choosing \( N_b = 50, \ 100 \), or 200 values of this effective exponent \( \xi \) in a similar range are found (Fig. 7). Of course, one must be aware that there is no strict one-to-one correspondence between the meaning of chain lengths \( N_b \) and \( N \) in different models; actually there may be the need for conversion factors \( N_b^{\text{BFM}}/N_b^{\text{BS}} \) and \( N^{\text{BFM}}/N^{\text{BS}} \) between the BS model and the BFM. The same fact is true when we compare simulations to experiments; e.g., the data of Rathgeber et al.\(^{42} \) could be mapped to the BFM (Ref. 26) implying an equivalence between \( N_b^{(\text{exp})} = 400 \) and \( N_b^{(\text{BFM})} = 259 \) and between \( N^{(\text{exp})} = 62 \) and \( N^{(\text{BFM})} = 48 \), for instance. We also note that with decreasing temperature \( \langle R_{eb}^2 \rangle \) decreases, irrespective of \( N \) (and also \( \xi \) decreases). Again we remind the reader that this parameterization of our data in terms of effective exponents (also used in related experimental work\(^{17,42} \)) only can serve to indicate the place in an extended crossover region to which the data belong.

When we analyze the gyration radius of the backbone as a function of backbone chain length for the BS model (Fig. 8) we find that over a restricted range of \( N_b \) one can fit the data by effective exponents again, \( \langle R_{eb}^{2(\text{exp})} \rangle^{1/2} \propto N_b^{\nu_{\text{eff}}} \), with \( 0.55 \leq \nu_{\text{eff}} \leq 0.95 \), and it is seen that \( \nu_{\text{eff}} \) increases systematically with side chain length \( N \), and \( \nu_{\text{eff}} \) for \( T = 4.0 \) is larger than for \( T = 3.0 \), for the same choice of \( N \). Of course, this variation of the effective exponent is a reflection of a gradual crossover from the rodlike regime \( \langle R_{eb}^2 \rangle^{1/2} \propto N_b \) to the self-avoiding walk (SAW)-like behavior of swollen coils \( \langle R_{eb}^{2(\text{exp})} \rangle^{1/2} \propto N_b^{\nu} \), with \( \nu \approx 0.588 \) in the good solvent regime \( (T = 4.0) \) or Gaussian-like coils \( \langle R_{eb}^{2(\text{exp})} \rangle^{1/2} \propto N_b^{1/2} \) for the theta point \( (T = 3.0) \), respectively. Similar plots as in Fig. 8 but for the BFM are shown in Figs. 9(a) and 9(b). Due to the availability of equilibrated data for much longer backbone chain lengths \( N_b \) for the BFM, the plot of \( \langle R_{eb}^2 \rangle / (2N_b^{2} N_b^2) \) versus \( N_b \) (Fig. 9(c)) indeed shows that the data settle down to a horizontal plateau implying that the asymptotic region, where Eq. (9) can be applied indeed is reached. Instead of \( R_{eb}^2 \) in Eq. (9), we use \( R_{eb}^2 \) such that the estimate of the \( N \)-dependent effective persistence
length $l_p R_g$ is given by the horizontal line in Fig. 9(c). Actually, for fixed side chain length $N$ the different choices of $N_b$ can be collapsed on a master curve, when $N_b$ is rescaled by $s_{\text{blob}}$, which can be interpreted as an estimate for the number of segments per persistence length. In our previous work, we have shown that bottle-brushes under very good solvent conditions can be described as self-avoiding walks of effective “blobs,” having a diameter that is just twice the cross-sectional radius of the bottle-brush, and containing a number $s_{\text{blob}}$ of backbone monomers. Note that hence $s_{\text{blob}}$ is not a fit parameter, but has been determined independently. This data collapse on a master curve is demonstrated for the BFM for the case $\sigma = 1, N = 6, 12, 18,$ and 24 (Fig. 9(d)).

Since “the” persistence length of polymers in the standard textbooks is traditionally defined from the decay of bond orientational correlations along the chains, we next focus on this quantity. Defining the bond vectors $\vec{a}_i$ in terms of the monomer positions $\vec{r}_i$ as $\vec{a}_i = \vec{r}_{i+1} - \vec{r}_i, i = 1, \ldots, N_b - 1$, this bond orientational correlation is defined as

$$\langle \cos \theta(s) \rangle = l_b^{-2} \frac{1}{N_b - 1 - s} \sum_{i=1}^{N_b-1-s} (\vec{a}_i \cdot \vec{a}_{i+s}).$$  

(11)

Note that $\langle \vec{a}_i^2 \rangle = l_b^2$ and hence $\langle \cos \theta(0) \rangle = 1$, of course. Considering the limit $N_b \to \infty$, and assuming Gaussian chain statistics, one obtains an exponential decay, since then $\langle \cos \theta(s) \rangle = \langle \cos \theta(1) \rangle^s = \exp[s \ln \langle \cos \theta(1) \rangle]$, and thus

$$\langle \cos \theta(s) \rangle = \exp[-s l_b^2 / l_p], \quad l_p^{-1} = -\ln \langle \cos \theta(1) \rangle / l_b.$$  

(12)

However, it has been shown by scaling and renormalization group arguments and verified by simulations that in the good solvent case there actually occurs a power law decay

$$\langle \cos \theta(s) \rangle \propto s^{-\beta}, \quad \beta = 2(1 - \nu) \approx 0.824, \quad s \to \infty,$$

(13)

while for chains at the theta point or in melts, one has

$$\langle \cos \theta(s) \rangle \propto s^{-3/2}, \quad s \to \infty.$$  

(14)

As far as bond orientational correlations are concerned, Gaussian chain statistics hence is misleading for polymers, under all circumstances. However, Shrivanyants et al. suggested that for semiflexible polymers (at the theta point), one can use still Eq. (12) but only for $1 \leq s \leq s^*$, where $s^* \propto l_p / l_b$ controls the crossover from the simple exponential decay, Eq. (12), to the power law, Eq. (14). Indeed, for a simple SAW model on the simple cubic lattice, where chain stiffness was controlled by an energy cost $\epsilon_b$ when the chain makes a $90^\circ$ kink on the lattice, it was shown that this suggestion works qualitatively, also in the good solvent case, with $l_p \propto \exp(\epsilon_b / k_B T)$ for $\epsilon_b / k_B T \gg 1$, although the crossover between Eqs. (12) and (13) is not sharp but rather spread out over a decade in the variable $s$.

Motivated by this finding, Figs. 10 and 11 hence present a few examples where $\langle \cos \theta(s) \rangle$ is plotted vs. $s$ on a semi-log plot, to test for a possible applicability of Eq. (12) for not too large $s$. However, we find that in fact Eq. (12) does NEVER hold for small $s$ ($s = 1, 2, 3$), unlike the semiflexible SAW model of Ref. 11, rather there occurs a very fast decay of $\langle \cos \theta(s) \rangle$ following a strongly bent curve (only two
successive values of $s$ can always be fit to a straight line, of course, but there is never an extended regime where a straight line through the origin, $⟨\cos θ(s = 0)⟩ = 1$, would be compatible with the data. It is also remarkable that this initial behavior is almost independent of $N$ and $T$; an obvious interpretation is that the stiffening of the backbone caused by the presence of long side chains is effective only on mesoscopic length scales along the backbone, but not on the scale of a few subsequent backbone bonds, which maintain a high local flexibility. Only for $s ≥ 4$, the data are compatible with a relation

$$⟨\cos θ(s)⟩ = a \exp(-bs), \quad 4 ≤ s ≤ s_{\text{max}}, \quad (15)$$

where $a$ and $b$ are phenomenological constants, and $s_{\text{max}}$ depends on both $N$, $σ$, and $T$ distinctely (but cannot be accurately obtained from our simulations, because for $⟨\cos θ(s)⟩ ≤ 0.03$ the statistical accuracy of the data deteriorates.) Obviously, the relation (Eq. (12)) $l_p^{-1} = -\ln(\cos θ(1))/\ell_b$ fails, but it seems tempting to identify an effective persistence length $l_p^{\text{eff}}$ as $l_p^{\text{eff}}/\ell_b = b^{-1}$. However, when we would define the persistence length in this way, we obtain the result that $l_p^{\text{eff}}$ depends on both $N_b$ and on $T$, not only on the side chain length $N$ and grafting density $σ$ (Fig. 12 and Table I). For the bead-spring model, one often estimates that the length unit ($σ_{\text{LJ}} = 1$) physically corresponds to about 0.5 nm. The data for $l_p^{\text{eff}}(T)$ at $σ = 1$ and good solvent conditions for $N_b = 200$ then would span a range from about 5 to about 40 nm, i.e., a similar range as proposed in recent experiments\(^6\). But already our previous work on the athermal bond fluctuation model\(^6\) has given some evidence, that defining a persistence length from a fit of the data for $⟨\cos θ(s)⟩$ to Eq. (15) is not suitable to obtain a measure of the local intrinsic stiffness, since $l_p^{\text{eff}}$ depends on $N_b$. The present data show that $l_p^{\text{eff}}$ depends on $T$ as well and, hence, is not just controlled by the chemical architecture of the bottle-brush (via the parameters, $σ$, $N$, and $N_b$), but depends on solvent conditions as well.

Thus, we argue that the physical significance of a persistence length $l_p^{\text{eff}}$ extracted from bond orientational correlations in this way is very doubtful, even at the theta point. We also note that sometimes, due to curvature on the semi-log plot (e.g., Fig. 11(d)) such fits are ill-defined.

Finally, we consider the possible validity of the Kratky-Porod result for the end-to-end distance of the chains at the theta temperature, where for $N_b → ∞$ we have (apart from logarithmic corrections) $⟨R^2⟩ ≃ N_b$, i.e., for this property a formula analogous to Gaussian chains holds. The Kratky-Porod result describes the crossover from rods to Gaussian

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**FIG. 9.** Log-log plot of $(R_g^2)^{1/2}/\ell_b$ for the bond fluctuation model versus backbone chain length $N_b$, for $67 ≤ N_b ≤ 259$, and several side chain lengths $N$, for $σ = 0.5$ (a) and $σ = 1.0$ (b). Part (c) shows the plot of rescaled radius of gyration $(R_g^2)/(2N_b^2)$ of the bottle-brush polymers versus $N_b$ for $σ = 1.0$. The persistence length $l_p^{\text{eff}}$ is determined by the values of plateau. Part (d) shows a crossover scaling plot, collapsing for $N = 6, 12, 18,$ and $24, σ = 1.0$, and all data for $67 ≤ N_b ≤ 1027$ on a master curve, that describes the crossover from rods $(R_g^2)^{1/2} ∝ N_b$ to swollen coils $(R_g^2)^{1/2} ∝ N_b^α, v = 0.588$. For this purpose, $N_b$ is rescaled with the blob diameter $s_{\text{blob}}$, which has been determined to be $s_{\text{blob}} = 6, 10, 12,$ and $14$ for $N = 6, 12, 18,$ and $24$, respectively.\(^6\)^
FIG. 10. Semi-log plot of \( \langle \cos \theta(s) \rangle \) vs. \( s \) for the bead-spring model with \( \sigma = 0.5 \). Data are chosen for \( N_b = 50 \) (a) (b) and \( N_b = 200 \) (c) (d) at \( T = 3.0 \) (a) (c) and \( T = 4.0 \) (b) (d), respectively. Several choices of \( N \) are shown as indicated. Straight lines illustrate fits to \( a \exp(-bs) \), with constants \( a, b \) quoted in the figure.

FIG. 11. Semi-log plot of \( \langle \cos \theta(s) \rangle \) vs. \( s \) for the bead-spring model with \( \sigma = 1.0 \) and \( \sigma = 4.0 \) (b) (d), respectively. Several choices of \( \sigma \) are shown as indicated. Straight lines illustrate fits to \( a \exp(-bs) \), with constants \( a, b \) quoted in the figure.

\[
\frac{\langle R_s^2 \rangle}{2l_p L} = 1 - \frac{l_p}{L} \left[1 - \exp(-L/l_p)\right].
\]  

We can define an effective exponent \( \nu_{\text{eff}}(L/l_p) \) in terms of the logarithmic derivative of this function, Figs. 13(a) and 13(b),

\[
\frac{d \ln \left[\langle R_s^2 \rangle/(2l_p L)\right]}{d \ln(L/l_p)} = 2 \nu_{\text{eff}}(L/l_p) - 1. 
\]  

Using the data for \( \nu_{\text{eff}} \) at \( N_b = 100 \) from Figs. 8(a) and 8(c) (and similar data not shown for \( \langle R_s^2 \rangle \)) we hence obtain estimates for the ratios \( L/l_p \) for the various choices of \( N \) for both \( \sigma = 0.5 \) and \( \sigma = 1 \). Note that the errors in our estimation of \( \nu_{\text{eff}} \) translate into rather large errors in our estimates for \( L/l_p \) (both these errors of our data are indicated in Figs. 13(a) and 13(b)). Since we expect that the actual variation of \( \langle R_s^2 \rangle \) with \( N_b \) exhibits slight curvature (although this is hardly detected in Figs. 8(a) and 8(c)), we use only this intermediate value of \( N_b = 100 \) to estimate the relation between \( N \) and \( L/l_p \), and we use neither \( N_b = 50 \) nor \( N_b = 200 \) for this purpose.

If the contour length \( L \) of the Kratky-Porod model, Eq. (16), would simply be the “chemical” contour length \( L_{\text{ch}} = N_bl_p \), where the bond length \( l_p \) connecting two neighboring monomers along the backbone is \( l_p \approx 1 \), our results for \( L/l_p \) would readily yield explicit results for \( l_p \). However, using then Eq. (16) to compute \( \langle R_s^2 \rangle/L^2 \) yields an overestimation by about a factor of 5 for \( \sigma = 1 \). This discrepancy proves that \( L \) is significantly smaller than \( L_{\text{ch}} \). Since Eq. (17) implies that there is a unique correspondence between \( \nu_{\text{eff}} \) and the ratio \( l_p/L \), the factor of five discrepancy for \( \langle R_s^2 \rangle \) (which is
TABLE I. Estimates of the effective persistence length $l_p^{eff}$ shown in Fig. 12 are listed for the BS model with the grafting densities $\sigma = 0.5$ and 1.0 at temperatures $T = 3.0$ and 4.0. Various values of the backbone length $N_b$ and the side chain length $N$ are chosen here. All length quoted in this table are given in units of $\ell_b$ (with $\ell_b \approx 0.97\ell_L$). Note that $l_p^{eff}$ depends not only on $N$ and $\sigma$, but also on $N_b$ and $T$, and hence does not seem as a characteristic of intrinsic chain stiffness. Estimates of $l_p(N)$ shown in Fig. 13 are also listed for comparison.

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<th>$l_p^{eff}/\ell_b$ ($T = 4.0$)</th>
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$N/l_p(N)$ ($T = 3.0$) | $N/l_p(N)$ ($T = 3.0$) | $N/l_p(N)$ ($T = 3.0$) | $N/l_p(N)$ ($T = 3.0$)
---|---|---|---
5 | 23.11 | 11.89 |
10 | 36.43 | 23.98 |
20 | 43.59 | 52.60 |
40 | 91.64 | 103.09 |

The data shown in Figs. 13(a) and 13(b) to obtain explicit estimates for $l_p(N)$, taking into account $L = N_b l_p^{eff}$ instead of $L = N_b/\ell_b$. Interestingly, the mechanisms leading to $l_p^{eff} < 1$ is also evident in the presence of the constant $a < 1$ in the fits of $\langle \cos(\theta(s)) \rangle = a \exp(-bs)$ in Figs. 10 and 11. Using then the estimates $l_p^{eff}(\sigma = 0.5, 0.33$ and $l_p^{eff}(\sigma = 1) \approx 0.45$, the data for $R_{eb}^2/2l_p(N)L$ at $T = 3.0$ are roughly compatible with Eq. (16), when we use $Ll_p(N)$ from Figs. 13(a) and 13(b) and take $L = l_p^{eff}N_b$ as is shown in Figs. 13(c) and 13(d). In this way, we have defined a correction factor $a = (l_p^{eff})^{-2}$ in Fig. 13, which was assumed to depend neither on $N$ nor on $N_b$. Note that while only $N_b = 100$ was used in Figs. 13(a) and 13(b), data for $N_b = 50,$ and 200 are included in Figs. 13(c) and 13(d). The resulting values of $l_p(N)$ which hence by construction do not depend on $N_b$ (Table I) are considered to be the most reliable estimates for the considered model. However, we emphasize that Eq. (16) for bottle-brushes is useful only if the solution is at theta conditions, but not in the good solvent regime. Using the data for $\nu_{eff}$ at $N_b = 100$ from Figs. 8(a) to 8(c) (and similar data not shown for $\langle R_{eb}^2 \rangle$) we hence obtain estimates for the ratios $Ll_p$ for the various choices of $N$ for both $\sigma = 0.5$ and $\sigma = 1.$
IV. CONCLUSIONS

In the present paper, a coarse-grained bead-spring model for bottle-brush polymers was studied by molecular dynamics methods, varying both the chain length \( N_b \) of the backbone and of the side chains \( (N) \), for two values of the grafting density, under variable solvent conditions. The main emphasis of the present work was a study of the various characteristic lengths describing the conformation of the macromolecule, contrasting the behavior under theta conditions with the behavior in the good solvent regime. Also a comparison with corresponding results for the bond fluctuation model has been performed; this athermal model represents very good solvent conditions, and while for corresponding parameters it yields results that are rather similar to the results for the bead-spring model in the good solvent regime, it has the advantage that much larger values of \( N_b \) can be studied.

Among the quantities that have been studied are the end-to-end distances of side chains and of the backbone, as well as the respective gyration radii, but also mesoscopic lengths that are particularly popular when a description in terms of the Kratky-Porod wormlike chain model is attempted, namely, “the” persistence length and “the” contour length of the wormlike chain. We have shown that for the range of rather short side chain lengths \( N \) that is only accessible, either in simulation or experiment, one often finds that a description in terms of power laws with effective exponents is adequate.

Specifically, the side chain radii vary as \( \langle R^2_s \rangle^{1/2} \propto N^{\nu_{eff}} \), and \( \nu_{eff} \approx 0.60 \) (at the theta temperature \( T = T_\theta \)) or \( \nu_{eff} \approx 0.63 \) to 0.66 (in the good solvent regime), see Fig. 3. These effective exponents (for the present models with flexible backbones) are the same as for otherwise equivalent models with stiff backbones and also are practically independent of the backbone chain length. While the resulting effective exponents are systematically smaller than the asymptotic values predicted theoretically for the limit \( N \to \infty \), \( \nu \approx 0.74 \) (good solvents) or \( \nu = 2/3 \) (theta solvents), respectively, they are comparable to the results of pertinent experiments: Zhang and co-workers\(^1,16,65\) report \( \nu_{eff} \approx 0.67 \) for a bottle-brush, where the chemical nature of the main chain and the side chains is identical. For other systems exponents in the range 0.56 \( \leq \nu_{eff} \leq 0.67 \) are reported,\(^17\) again values comparable to our findings. Some experimental studies also report that somewhat different results occur when different solvents are used,\(^1,4,12,17,18\) but a systematic variation of solvent quality to our knowledge has not yet been performed. Our results have shown that for \( T \geq T_\theta \), the side chain radii vary only very weakly with temperature (which in our model causes the change in solvent quality), see Fig. 4.

Also the backbone end-to-end distance shows a power law variation with the side chain length, \( \langle R^2_b \rangle \propto N^5 \) (Figs. 5–7), reflecting thus the systematic backbone stiffening with increasing side chain length. In this case, however, the effective exponent depends on the backbone chain length \( N_b \),

![Image of graphs showing the effective exponents](image-url)

FIG. 13. Plot of the function \( \nu_{eff}(L/l_p) \) versus \( L/l_p \) as predicted from the Kratky-Porod model, Eqs. (16) and (17) (full curves). The numbers for \( L/l_p \) extracted for \( \sigma = 0.5 \) (a) and \( \sigma = 1.0 \) (b) are quoted in the figure for various \( N \) at the abscissa. The average of the exponents \( \nu_{eff} \) from Figs. 8(a) and 8(c) and from \( R^2_{eh} \) (not shown) are quoted on the ordinate. Log-log plot of \( \nu_{eff} \) for \( \sigma = 1.0 \) (c) (d). Several choices of \( N \) are shown as indicated. Data plotted by the same symbol correspond to specific data collapse are obtained by introducing a factor of \( \sigma = 0.5 \) (a) and \( \sigma = 1.0 \) (b).
for \( N_b \leq 300 \), before a saturation at \( \eta \approx 0.65 \) (\( \sigma = 0.5 \)) or 0.75 \( (\sigma = 1) \) occurs, in the case of the bond fluctuation model. Even somewhat larger exponents are observed for the bead-spring model (up to \( \eta \approx 0.88 \), Fig. 7).

A further effective exponent describes the variation of the backbone end-to-end distance and gyration radius with backbone chain length (Figs. 8 and 9). We have interpreted this variation as a crossover from rodlike behavior at small \( N_b \) to self-avoiding walk like behavior (under good solvent conditions) or random walk like behavior (under theta conditions) with increasing \( N_b \).

Finally, “the” persistence length has been estimated in various ways, and demonstrating that the different estimates are not mutually consistent with each other, it was argued that a unique persistence length does not exist. While a regime of exponential decay of the bond autocorrelation function often can be observed over some intermediate range of contour distances (Figs. 10 and 11), the resulting estimates for a persistence length do not only depend on side chain length \( N \) and grafting density \( \sigma \), but also on backbone chain length \( N_b \) and on temperature \( T \) (Fig. 12). However, when one studies the variation of the end-to-end distance of the backbone for \( T = T_\theta \), an analysis in terms of the Kratky-Porod wormlike chain model (Eq. (16)) becomes feasible (Fig. 13). But one must not identify the contour length \( L \) implied by this model with the “chemical” contour length \( L_{\text{ch}} = N_b l_b \), where \( l_b \) is the actual bond length, but rather one has \( L = N_b \eta \text{eff} \) with \( \eta \text{eff} \) distinctly smaller than \( l_b \). This effect results from the flexibility of the backbone on small scales; only on the scale of several backbone bonds does the stiffening due to the mutual side chain repulsions come into play. Thus, at the theta point both an effective contour length \( L \) and a persistence length \( \eta \text{eff}(N) \) are well-defined quantities, in terms of a fit of the data to the Kratky-Porod model, while under good solvent conditions such an analysis is not appropriate.

We hope that the present work stimulates some more systematic experimental work on these issues. Of course, for real bottle-brushes where the chemical nature of the backbone often differs from the side chains, the interesting possibility arises that the backbone and the side chains have rather different theta temperatures. Another subtle issue concerns the precise location of theta conditions. While we expect that for the limit \( N_b \to \infty \) at fixed ratio \( N/N_b \), the theta conditions coincide with the theta conditions for simple linear polymers (\( N_b \to \infty, N = 0 \)), it is not clear whether the location of the theta point for the limit \( N_b \to \infty \) at fixed (small) \( N \) depends significantly on \( N \). Thus, also more theoretical work clearly is needed.

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